



Spacecraft Formation Flying

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Introduction

- ▶ Formation Flying Problem
- ▶ Describing Relative Orbits
- ▶ Perturbations and Control Systems
- ▶ The CanX-4&5 Nanosatellite Mission

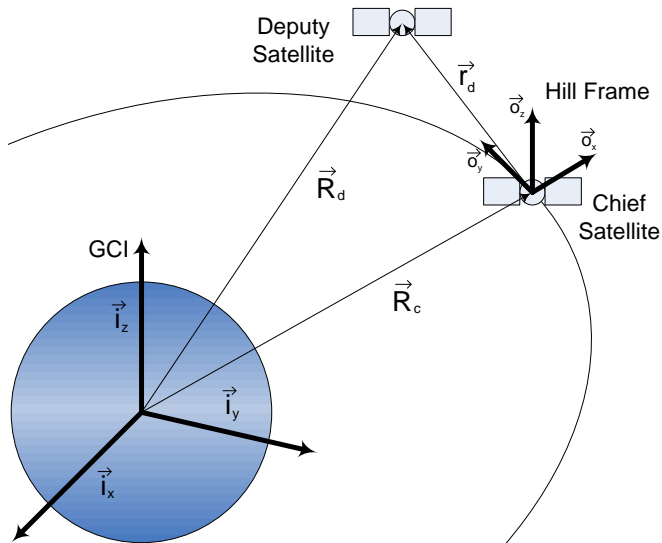




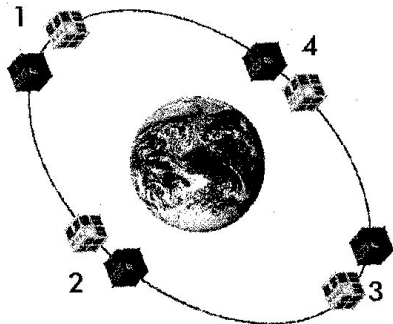
Formation Flying

- ▶ **Problem:** Maintain bounded relative motion between 2 or more satellites
- ▶ **Motivation:** Accomplish things that one large (expensive) satellite can do with many smaller satellites
- ▶ **Advantages:** Inherently redundant
- ▶ **Applications:** communications, remote sensing

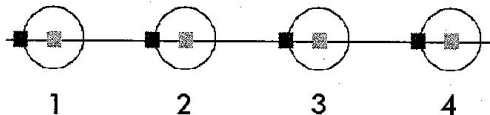
The Basic Setup



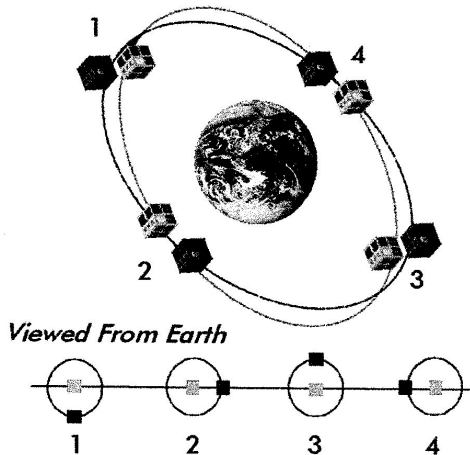
The Along Track Orbit (ATO)



Viewed From Earth



The Projected Circular Orbit (PCO)





Perturbations in Low Earth Orbit

Reasons we need a control system:

- ▶ the chief is not in a perfectly circular orbit
- ▶ oblateness of the Earth (it's fat at the equator)
- ▶ differential atmospheric drag



Control System Design

- ▶ Place thrusters on the deputy
- ▶ Measure the relative position using GPS
- ▶ Determine errors: difference between actual relative position and desired relative position
- ▶ Use negative feedback: thrust in opposite direction of the errors
- ▶ Thrust is proportional to size of the errors



Numerical Example

Chief Orbit

initially circular:

$$\text{radius} = 6378 \text{ km} + 550 \text{ km}$$

Deputy Orbit

PCO relative initial conditions:

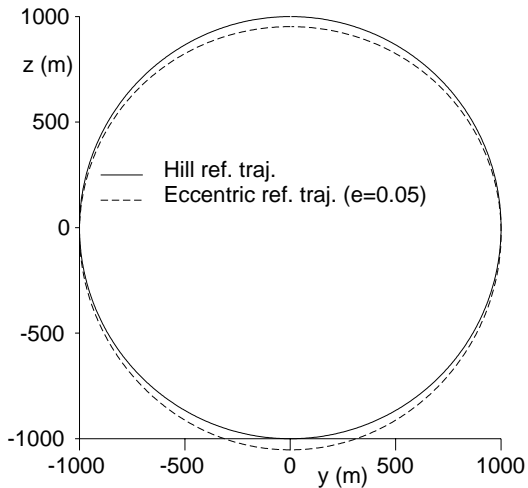
$$\text{radius} = 1000 \text{ m}$$

Controller Design

- ▶ Try to keep relative position errors less than 1 metre while using as little fuel as possible

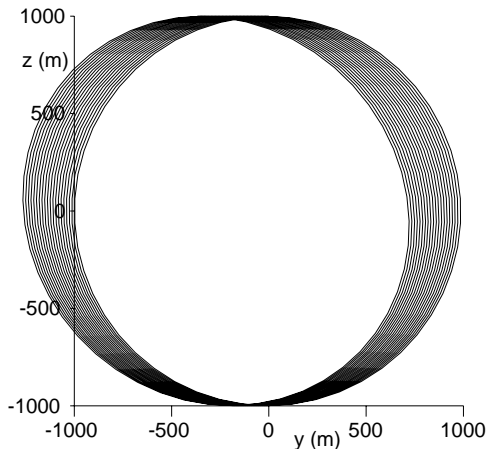


Desired Relative Orbit



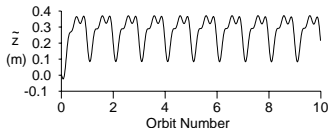
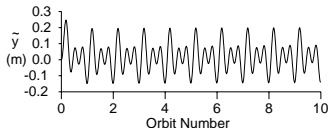
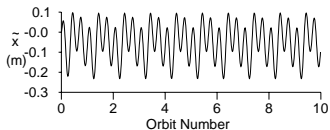


Open-Loop Response with Oblateness Perturbation (No Control System)





Closed-Loop Response with Oblateness Perturbation (With Control System)



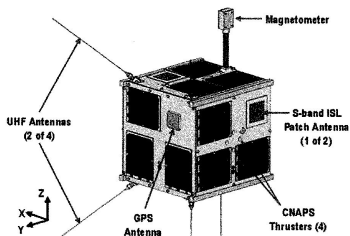
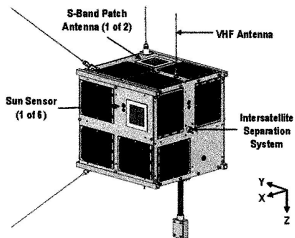


The CanX-4&5 Mission

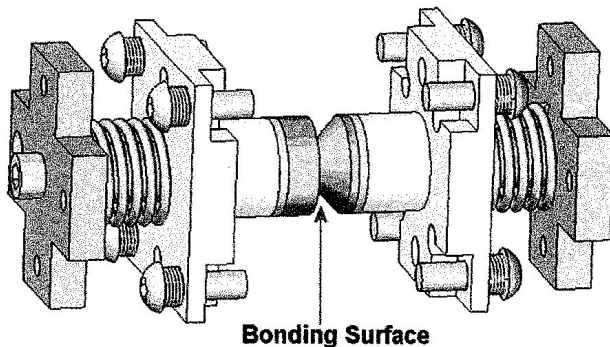
CanX = Canadian Advanced Nanosatellite eXperiment

- ▶ two identical 6.85 kg nanosatellites
- ▶ 20 cm cubes
- ▶ position error requirement: < 1 m
- ▶ position determination: < 10 cm
- ▶ total Δv : 14 m/s
- ▶ thrust: 5 mN

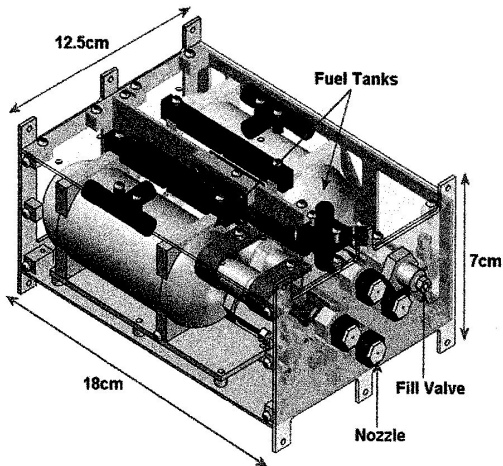
The CanX-4&5 Spacecraft



Intersatellite Separation System



Canadian Nanosatellite Propulsion System

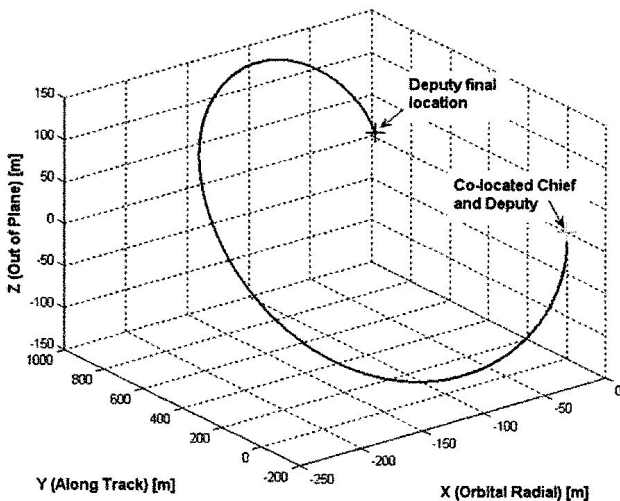




CanX-4&5 Mission Sequence

- ▶ Separation Sequence
- ▶ **1000 m ATO** (50 orbits)
- ▶ ATO-to-ATO reconfiguration
- ▶ **500 m ATO** (50 orbits)
- ▶ ATO-to-PCO reconfiguration
- ▶ **50 m PCO** (50 orbits)
- ▶ PCO-to-PCO reconfiguration
- ▶ **100 m PCO** (50 orbits)

Separation Maneuver





Concluding Remarks

- ▶ Formation Flying is an interesting problem in spacecraft dynamics and control
- ▶ ATO and PCO relative orbits are useful in applications
- ▶ CanX-4&5 will demonstrate autonomous formation flying in low Earth orbit using a pair of nanosatellites